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**Index Terms**— Microwave measurements, calibration, coplanar waveguides.

**Abstract**— The condition imposed by the Lorentz reciprocity theorem, a field property, on microwave circuit parameters is derived. The effect of power consistency and renormalization is discussed. A robust multi-reflect Thru-Line-Reflect error box completion scheme is presented. The relative calibration is then converted into an absolute calibration using error box reciprocity.

## 1 Introduction

Reciprocity of a two-port junction is a necessary condition for the determination of the forward and reverse transmission if only their product is known, as obtained from e.g. SOL or TLR calibration techniques. Equating both quantities[1, p. 159] is not always valid as shown in [2]. An absolute determination requires power meters and phase standards, which are not readily available for e.g. coax to coplanar waveguide junctions.

The condition reciprocity imposes on the microwave circuit parameters depends on the underlying field phenomenon and on the normalization, which relates the field with the voltage and current. This paper decouples reciprocity and normalization. It also shows that power consistency, between the field and the circuit parameters, simplifies the reciprocity relation for most practical junctions. Formulas valid for any normalization are developed and the reciprocity ratio  $S_{21}/S_{12}$  for Marks' traveling wave intensities[2] is recalculated.

TLR employs two transmission lines and two equal reflects for the determination of the 7-term error model. From the thru-line data follows[3] the line propagation constant and two relations per error box. The calibration is completed via the thru S-parameters and one equation from the reflect measurement. The standard algorithm[4] uses the error box reflection's reciprocal,  $1/S_{x22}$ , which is undefined

if  $S_{x22}$  is zero up to measurement precision. Spike errors may appear when sequencing calibration comparison, e.g. when modelling a capacitor via TLR.

The here presented algorithm completes the error boxes using its transmission coefficients. Requiring non-zero transmission does not introduce a deficiency since this is essential for any deembedding technique. All intermediate results are bounded, well defined, and approach a constant value for the ideal case. Moreover, the calculation sequence exploits the problem symmetry and aims for robustness. Redundant data is explicitly demonstrated, allowing for a real time error estimate. The algorithm is further extended to include Line-Reflect-Match and the zero- and multi-reflect case. Finally, the 8-term absolute error model is computed assuming reciprocity.

## 2 Reciprocity

A voltage current, or voltage S-parameter, circuit representation is a compact way of describing a field problem. This equivalence is possible if the field components of the incident and reflected wave are either in phase or in counter-phase. The fields at port  $i$  thus satisfy

$$\begin{aligned} [\vec{E}_i, \vec{H}_i] &= [\vec{e}_{ti} + \vec{e}_{zi}, \vec{h}_{ti} + \vec{h}_{zi}] C_{0i}^+ e^{-\gamma_i z} \\ &+ [\vec{e}_{ti} - \vec{e}_{zi}, -\vec{h}_{ti} + \vec{h}_{zi}] C_{0i}^- e^{\gamma_i z} \quad (1) \end{aligned}$$

with  $\vec{e}, \vec{h}$  the  $z$ -independent modal fields and  $C_0^+, C_0^-$  the two wave amplitude constants. A normalization relates the transverse components  $\vec{e}_t, \vec{h}_t$  with  $V_c, I_c$ , the modal voltage and current, and sets the characteristic line impedance. The wave voltages at port  $i$ ,  $V_0^+$  and  $V_0^-$ , determine the fields since

$$C_{0i}^\pm = \frac{V_{0i}^\pm}{V_{ci}} = \frac{I_{0i}^\pm}{I_{ci}} \Rightarrow Z_{ci} = \frac{V_{ci}}{I_{ci}} = \frac{V_{0i}^+}{I_{0i}^+} = \frac{V_{0i}^-}{I_{0i}^-} \quad (2)$$

holds from (1). An arbitrary transversal field then follows from[1, p. 146]

$$\vec{E}_{ti} = \left( \frac{V_{0i}^+}{V_{ci}} e^{-\gamma_i z} + \frac{V_{0i}^-}{V_{ci}} e^{\gamma_i z} \right) \vec{e}_{ti} = \frac{V_i(z)}{V_{ci}} \vec{e}_{ti} \quad (3)$$

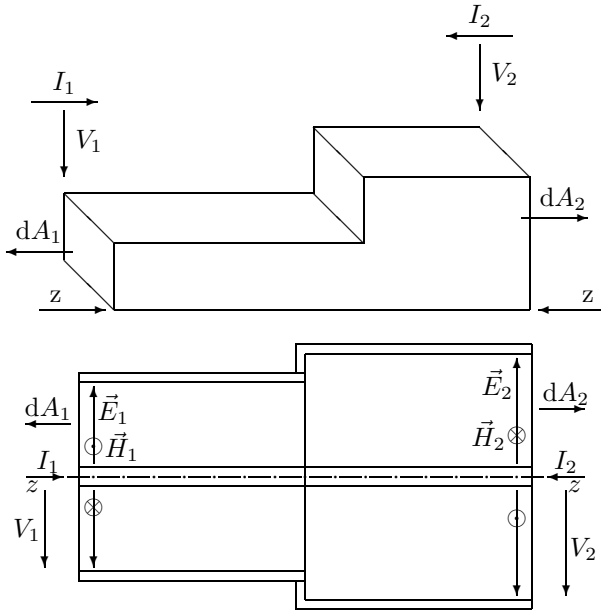


Figure 1: Examples of reciprocal microwave circuits. Top: A TE<sub>10</sub> E-plane step rectangular waveguide junction. Bottom: A TM dissimilar coaxial transmission line junction.

$$\vec{H}_{ti} = \left( \frac{I_{0i}^+}{I_{ci}} e^{-\gamma_i z} - \frac{I_{0i}^-}{I_{ci}} e^{\gamma_i z} \right) \vec{h}_{ti} = \frac{I_i(z)}{I_{ci}} \vec{h}_{ti} \quad (4)$$

with  $V$  and  $I$  the port voltage and current.

The Lorentz reciprocity theorem [1, pp. 57–59, 159] applied on a two-port source free junction, e.g. fig. 1, imposes a condition on the incident and reflected field. The Lorentz integral

$$\oint_A (\vec{E}^I \times \vec{H}^{II} - \vec{E}^{II} \times \vec{H}^I) d\vec{A} = 0 \quad (5)$$

over the junction enclosing surface  $A$  reduces to the two terminal planes if the remaining surface is perfectly conducting, characterized by a scalar surface impedance, or is infinitely far away. Substituting the fields in terms of (1) relates the wave amplitudes. The integrand simplifies to the transverse components if  $\vec{e}_t, \vec{h}_t$  are parallel, and if  $\vec{e}_z, \vec{h}_z$  are normal, to the terminal plane. TE and TM waves [1, p. 72] satisfy this condition. Choosing sources outside of the junction such that  $\vec{E}_{t2}^I = 0$ , experiment  $I$ , and such that  $\vec{E}_{t1}^{II} = 0$ , experiment  $II$ , with (3–4) gives

$$\frac{V_2^{II} I_2^I}{V_1^I I_1^{II}} = \frac{\frac{1}{V_{c1} I_{c1}} \int_{A_1} \vec{e}_{t1} \times \vec{h}_{t1} d\vec{A}}{\frac{1}{V_{c2} I_{c2}} \int_{A_2} \vec{e}_{t2} \times \vec{h}_{t2} d\vec{A}} \quad (6)$$

or with the reciprocity factor

$$K_i = \frac{1}{V_{ci} I_{ci}} \int_{A_i} \vec{e}_{ti} \times \vec{h}_{ti} \cdot \vec{u}_z dA \quad (7)$$

and (2) in

$$\frac{Y_{21}}{Y_{12}} = \frac{K_1}{K_2} \Leftrightarrow D = \frac{S_{21}}{S_{12}} = \frac{Z_{c2} K_1}{Z_{c1} K_2} \quad (8)$$

which agrees with [2, eq. 22]. The S-parameter reciprocity ratio  $D$  alternatively follows from (5) with port 2/1, experiment  $I/II$ , matched. A good choice of  $V_c, I_c$  sets  $K$  to unity and implies

$$\arg(K_i) = 0 \Leftrightarrow \arg(V_{ci} I_{ci}) = \arg(\vec{e}_{ti} \vec{h}_{ti}) \quad (9)$$

if the phase of the transverse field is constant in the terminal plane, e.g. for TE and TM waves.

### 3 Power consistency

The power transmitted across port  $i$  follows from

$$S_t = \frac{1}{2} \int_A \vec{E}_t \times \vec{H}_t^* \cdot \vec{u}_z dA \quad (10)$$

if the transverse components are parallel, and the axial components normal, to the terminal plane. Substituting (3–4) and defining the modal power

$$S_c = \frac{1}{2} \int_A \vec{e}_t \times \vec{h}_t^* \cdot \vec{u}_z dA, \quad (11)$$

the power carried by the forward modal field, yields

$$S_t = \frac{VI^*}{V_c I_c^*} S_c = (C^+ + C^-)(C^+ - C^-)^* S_c \quad (12)$$

which agrees with the circuit power  $\frac{1}{2} VI^*$  only if

$$S_c = \frac{1}{2} \int_A \vec{e}_t \times \vec{h}_t^* \cdot \vec{u}_z dA = \frac{1}{2} V_c I_c^* \quad (13)$$

holds. From this power consistency follows

$$Z_c = \frac{V_c}{I_c} = \frac{|V_c|^2}{2S_c} = \frac{2S_c}{|I_c|^2} = \frac{\int_A Z_w \vec{h}_t \vec{h}_t^* dA}{|I_c|^2}, \quad (14)$$

uniquely determining the phase of  $Z_c$  [5], and

$$\arg\left(\frac{2S_c}{V_c I_c^*}\right) = 0 \Leftrightarrow \arg(V_c I_c^*) = \arg(\vec{e}_t \vec{h}_t^*) \quad (15)$$

if the modal field's phase is constant in the terminal plane. If  $V_c$  is in phase with  $\vec{e}_t$  or if  $I_c$  is in phase with  $\vec{h}_t$ , e.g. defined by a path integral for TM waves or by a contour integral for TE waves, then (9) holds from (15), and  $K = 1$  follows from (13). Converse, (9) and (15) can only be satisfied if the modal voltage and current are in phase with their corresponding field component. In general, if two out of the four conditions

$$\begin{aligned} \arg(K) = 0 & & \arg\left(\frac{2S_c}{V_c I_c^*}\right) = 0 \\ \arg(V_c) = \arg(\vec{e}_t) & & \arg(I_c) = \arg(\vec{h}_t) \end{aligned} \quad (16)$$

are satisfied, then the remaining conditions hold and

$$K = 1 \Leftrightarrow \frac{2S_c}{V_c I_c^*} = 1 \quad (17)$$

follows. Requiring a unit reciprocity factor and power consistency thus uniquely determines the phase of the modal voltage and current. A good definition has one degree of freedom, the magnitude  $|V_c|$  or  $|I_c|$ , proportional to the modal field, or the magnitude  $|Z_c|$ .

## 4 Renormalization

The two wave voltages  $V^+$ ,  $V^-$  at port  $i$  can be scaled by a constant. A good choice may simplify the reciprocity relation (8) or may set  $|V_n^+|^2/2$  equal to the true power. The renormalized  $V_c$ ,  $I_c$  follow from

$$V_{cni} = \frac{V_{ci}}{k_{vi}} \quad I_{cni} = k_{ii} I_{ci} \quad (18)$$

which scales

$$V_{ni}^\pm = \frac{V_i^\pm}{k_{vi}} \quad I_{ni}^\pm = k_{ii} I_i^\pm \quad (19)$$

and yields the normalized quantities

$$K_{ni} = \frac{V_{ci} I_{ci}}{V_{cni} I_{cni}} K_i = \frac{k_{vi}}{k_{ii}} K_i \quad (20)$$

$$Z_{cni} = \frac{V_{cni}}{I_{cni}} = \frac{Z_{ci}}{k_{vi} k_{ii}} \quad (21)$$

$$S_{cni} = \frac{1}{2} V_{cni} I_{cni}^* = \frac{k_{ii}^*}{k_{vi}} S_{ci} \quad (22)$$

$$\frac{Z_{cni}}{K_{ni}} = \frac{1}{k_{vi}^2} \frac{Z_{ci}}{K_i} \quad (23)$$

$$S_{nji} = \frac{k_{vi}}{k_{vj}} S_{ji} \quad (24)$$

$$D_{nji} = \frac{k_{vi}^2}{k_{vj}^2} \frac{Z_{cj} K_i}{Z_{ci} K_j} \quad (25)$$

with  $D_n$  the normalized reciprocity ratio. Conservation of reciprocity (20) and modal power (22) for the normalized voltage and current requires a real scale factor  $k_v = k_i$ .

Collin[1, p. 173] chooses  $k_v = \sqrt{Z_c}$  and implicitly sets  $k_i = k_v$ . This conserves reciprocity, transforms the characteristic impedance to unity and reduces the power to the apparent power. Setting  $k_i = k_v^*$  maintains the power equivalence but results in a non-standard reciprocity condition, see table 1. The normalized admittance matrix cannot describe the circuit unless  $Z_c$  is real.

These voltage normalized S-parameters remove the  $Z_c$  dependence of the reciprocity ratio.  $D_n$  becomes

$$D_n = \frac{S_{n21}}{S_{n12}} = \frac{Z_{cn2}/K_{n2}}{Z_{cn1}/K_{n1}} = \frac{S_{21} \sqrt{\frac{Z_{c1}}{Z_{c2}}}}{S_{12} \sqrt{\frac{Z_{c2}}{Z_{c1}}}} = \frac{K_1}{K_2}. \quad (26)$$

$k_{vi} = \sqrt{Z_{ci}}$	$k_{ii} = k_{vi}$	$k_{ii} = k_{vi}^*$
$Y_{21} = Y_{12} \Rightarrow$	$\frac{Y_{n21}}{Y_{n12}} = 1$	$\frac{Y_{n21}}{Y_{n12}} = \sqrt{\frac{Z_{c1} Z_{c2}}{Z_{c1}^* Z_{c2}^*}}$
$S_{cni} =$	$ S_{ci} $	$S_{ci}$
$Z_{cni} =$	1	$\sqrt{Z_{ci}/Z_{ci}^*}$
$\frac{ V_n^+ ^2}{2Z_{cni}} =$	$\frac{ V_n^+ ^2}{2 Z_{ci} }$	$\frac{ V_n^+ ^2}{2Z_{ci}}$

Table 1: The effect of the choice of  $k_i$ , when normalizing with  $k_v = \sqrt{Z_c}$ , on reciprocity, modal power, characteristic impedance and the power in a forward propagating wave. Left: reciprocity conservation. Right: power conservation

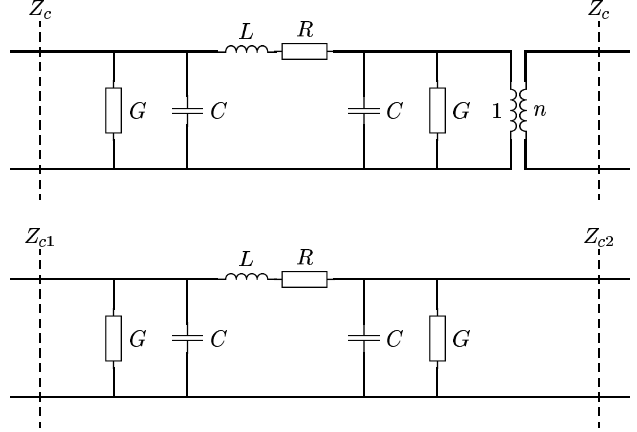


Figure 2: Typical equivalent circuits modelling reciprocal junctions. Top: The line impedance  $Z_c$  of a waveguide is usually chosen equal to the wave impedance  $Z_w$ . The step geometry difference is modelled by a voltage change. Bottom: Voltage continuity is typical for an ideal coaxial line junction. The geometry change yields a different line impedance. The normalized S-parameters coincide if  $n = \sqrt{Z_{c1}/Z_{c2}}$ .

Also, the normalized wave voltages are independent of a real prescaling factor, as follows from

$$\begin{cases} V_{cr} = \frac{V_c}{k_r} \\ I_{cr} = I_c k_r \end{cases} \Rightarrow \begin{cases} V_{cn} = \frac{V_{cr}}{\sqrt{Z_{cr}}} = \frac{V_c}{\sqrt{Z_c}} \\ I_{cn} = I_{cr} \sqrt{Z_{cr}} = I_c \sqrt{Z_c} \end{cases} \quad (27)$$

Thus, any good definition (16–17) of  $V_c$  and  $I_c$  for TE or TM waves yields the same normalized values, independent of the actual  $|V_c|$ ,  $|I_c|$  or  $|Z_c|$ . Moreover,  $K$  and  $D_n$  are then unity. The field follows from

$$C_i^\pm = \frac{V_i^\pm}{V_{ci}} = \frac{V_{ni}^\pm \sqrt{Z_{ci}}}{V_{ci}} = \frac{V_{ni}^\pm}{\sqrt{V_{ci} I_{ci}}} \quad (28)$$

with the denominator known from the modal solution.

Converse, a circuit interpretation of voltage normalized S-parameters requires an external estimate of  $|V_c|$ ,  $|I_c|$  or  $|Z_c|$ . The line impedance  $Z_c$  of a waveguide is usually chosen equal to the wave impedance,

which is constant over e.g. the  $E$ -plane step in fig. 1. The modal voltage at each port follows from power consistency [1, p. 162] (14), and depends on the waveguide height. For coaxial lines, the modal voltage  $V_c$  is best defined using a path integral in the terminal plane between the two conductors. This guarantees voltage continuity over an ideal junction and defines  $Z_c$ . Figure 2 shows typical equivalent circuits.

A relative calibration like SOL recovers the junction's  $S_{11}$ ,  $S_{22}$  and  $S_{21}S_{12}$ . Reciprocity is often used to normalize the  $S$ -parameters. Thus,

$$S_{r,sol} \approx \begin{bmatrix} S_{11} & kS_{12} \\ S_{21}/k & S_{22} \end{bmatrix}, \quad (29)$$

with  $k$  unknown, is usually normalized through

$$S_{n21} = S_{n12} = \sqrt{S_{r21}S_{r12}} \Leftrightarrow k = \sqrt{\frac{S_{21}}{S_{12}}} \quad (30)$$

setting  $D_n = 1$  and implicitly choosing

$$k_{vi} = \sqrt{\frac{Z_{ci}}{K_i}} \quad (31)$$

which coincides with the voltage normalized  $S$ -parameters if  $K$  is unity. The absolute on-wafer calibration of Agilent's Non-linear Network Measurement System uses this property. First, a SOL calibration between the probe port 2 and an auxiliary coax port b is performed [6]. Second, a power meter measures  $|V_b^-|$  for a  $V_2^+$ . Third, a phase standard excites  $V_b^+$  and  $V_2^-$  is measured. The absolute voltage waves at the probe follow from

$$\begin{bmatrix} V_2^- \\ V_2^+ \end{bmatrix} \sqrt{\frac{K_2}{Z_{c2}}} = T_n \begin{bmatrix} V_b^+ \\ V_b^- \end{bmatrix} \sqrt{\frac{K_b}{Z_{cb}}} \quad (32)$$

with  $T_n$  the normalized cascading wave matrix,  $Z_{c2}$  the on wafer line impedance and  $Z_{cb}$  the coaxial line impedance. This scaling is avoided by setting  $Z_{c2}$  equal to  $Z_{cb}$  before the absolute calibration, and assuming a unity reciprocity factor.

Marks defines two traveling wave intensities as

$$V_n^\pm = \sqrt{2\Re(S_c)} \frac{V^\pm}{V_c} = \frac{|V_c| \sqrt{\Re(Z_c)}}{|Z_c| V_c} V^\pm \quad (33)$$

with the property that  $|V_n^+|^2/2$  equals the true power, if all voltages are defined as peak values. Substituting  $k_v$  from above in equation (23) yields

$$\frac{Z_{cn}}{K_n} = \frac{1}{\frac{Z_c}{|V_c|^2} \int \vec{e}_t \times \vec{h}_t \cdot \vec{u}_z dA} \cdot \frac{1}{1 - j \frac{\Im(Z_c)}{\Re(Z_c)}} \quad (34)$$

from which  $D_n$  follows, equal to [2, eq. 21].

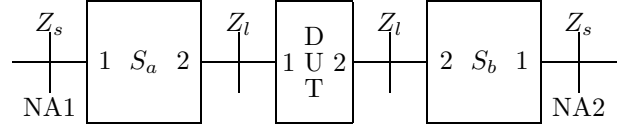


Figure 3: The TLR error box port numbering. The port 2 reference impedance is set by the line impedance  $Z_l$ .

## 5 TLR error box completion

From the thru-line measurement data follows an estimate of the line propagation constant  $\gamma$  and

$$\alpha_a \approx S_{a11} \quad \beta_a \approx \frac{S_{a22}}{\det(S_a)} \quad (35)$$

for error box  $a$ , see [3]. The here introduced port numbering, fig. 3, takes advantage of the problem symmetry. The relations for box  $x = [a, b]$  become

$$\alpha_x \approx S_{x11} \quad \chi_x = \frac{\beta_x}{\beta_x \alpha_x - 1} \approx \frac{S_{x22}}{S_{x21} S_{x12}}. \quad (36)$$

The thru or line data gives

$$c_a = S_{t11} - \alpha_a \approx \frac{S_{a21} S_{a12} e^{-2\gamma l} S_{b22}}{1 - S_{a22} e^{-2\gamma l} S_{b22}} \quad (37)$$

$$S_{t12} \approx \frac{S_{b21} e^{-\gamma l} S_{a12}}{1 - S_{a22} e^{-2\gamma l} S_{b22}} \quad (38)$$

$$S_{t21} \approx \frac{S_{a21} e^{-\gamma l} S_{b12}}{1 - S_{a22} e^{-2\gamma l} S_{b22}} \quad (39)$$

$$c_b = S_{t22} - \alpha_b \approx \frac{S_{b21} S_{b12} e^{-2\gamma l} S_{a22}}{1 - S_{a22} e^{-2\gamma l} S_{b22}} \quad (40)$$

and allows the calculation of  $e, p$  via

$$e = \frac{1}{2} \left( \frac{\chi_a c_a}{\chi_a c_a + 1} + \frac{\chi_b c_b}{\chi_b c_b + 1} \right) \quad (41)$$

$$\approx S_{a22} e^{-2\gamma l} S_{b22} \quad (42)$$

$$p = S_{t21} S_{t12} (1 - e)^2 \quad (43)$$

$$\approx S_{a21} S_{a12} S_{b21} S_{b12} e^{-2\gamma l} \quad (44)$$

with  $l$  the thru or line length. The two terms in (41) yield the same quantity and their difference is an indication of the measurement error. LRM inhibits the use of (41) since only  $\alpha$  is obtained from the match. The missing unknowns then follow from

$$e = \frac{c_a c_b}{S_{t21} S_{t12}} \quad \chi_a = \frac{c_b (1 - e)}{p} \quad \chi_b = \frac{c_a (1 - e)}{p} \quad (45)$$

with a lower accuracy compared to optimal TLR. Assuming one lossless line, ideal error boxes, and Marks' error model yields

$$\sigma_\chi^2 = \sigma_\beta^2 = \sigma_\alpha^2 = \frac{4\sigma_\delta^2}{|e^{\gamma l} - e^{-\gamma l}|^2} \quad (46)$$

$$\sigma_c^2 = 2\sigma_\delta^2 + \sigma_\alpha^2 \quad (47)$$

with  $\sigma_\delta$  modelling the contact imperfection. Clearly, using (45) in TLR calibrations results in loss of accuracy. Its use is only justified if a high line loss invalidates the linearized error analysis of [3, eqs. 21, 37, 38].

Further error box completion requires the measurement of an equal reflect at both ports. The data  $S_r$  relates

$$S_{a22} + \frac{S_{a21}S_{a12}}{S_{r11} - \alpha_a} \approx \frac{1}{\Gamma_r e^{-2\gamma l_r}} \approx S_{b22} + \frac{S_{b21}S_{b12}}{S_{r22} - \alpha_b} \quad (48)$$

with  $\Gamma_r$  the standard's reflection and estimates

$$a_a = S_{r11} - \alpha_a \quad a_b = S_{r22} - \alpha_b \quad (49)$$

$$\rho = \frac{\chi_a + 1/a_a}{\chi_b + 1/a_b} \approx \frac{S_{b21}S_{b12}}{S_{a21}S_{a12}}. \quad (50)$$

This measurement may be omitted if there is error box symmetry. Setting

$$a_a = \chi_b, \quad a_b = \chi_a \Rightarrow a_a \chi_a = a_b \chi_b \Leftrightarrow S_{a22} = S_{b22} \quad (51)$$

forces an equal port 2 reflection.

The measurement of multiple reflects yields as many estimates  $\rho$ . Averaging this data is done via the Gauss Markov theorem. Suppose the vector  $\vec{x}$  is the unknown parameter and that  $\vec{y}$  is the measurement data corrupted by the correlated error  $\vec{e}$ . The system thus obeys

$$\vec{y} = A\vec{x} + \vec{e} \quad (52)$$

with  $\vec{x}$ ,  $\vec{e}$  and  $\vec{y}$  stochastic vectors, and the property

$$E\{\vec{e}\} = \vec{0} \quad V_{ee} = E\{\vec{e}\vec{e}^+\} \quad (53)$$

$$V_{xy} = V_{xx}A^+ \quad V_{yy} = AV_{xx}A^+ + V_{ee} \quad (54)$$

where  $V$  is the covariance matrix. Given a realization  $\vec{y}$ , the conditional mean for  $\vec{x}$  can be calculated. For jointly Gaussian vectors, in real and imaginary part, the result for  $\vec{x}_{est} = E\{\vec{x}|\vec{y}\}$  is [7]

$$A^+V_{ee}^{-1}(\vec{y} - E\{\vec{y}\}) = (V_{xx}^{-1} + A^+V_{ee}^{-1}A)(\vec{x}_{est} - E\{\vec{x}\}), \quad (55)$$

using (54). The expression simplifies assuming a zero  $V_{xx}^{-1}$ , no a priori knowledge, yielding the linear unbiased estimator

$$\vec{x}_{est} = (A^+V_{ee}^{-1}A)^{-1}A^+V_{ee}^{-1}\vec{y} \quad (56)$$

$$= F\vec{y} = E\{\vec{x}|\vec{y}\} \quad (57)$$

$$E\{\vec{x}_{est}|\vec{y}\} = FA\vec{x} + FE\{\vec{e}\} = \vec{x} \quad (58)$$

$$\begin{aligned} V_{xx|y} &= E\{(\vec{x}_{est} - \vec{x})(\vec{x}_{est} - \vec{x})^+\} \quad (59) \\ &= FV_{ee}F^+ = (A^+V_{ee}^{-1}A)^{-1} \quad (60) \end{aligned}$$

which is minimum variance for any error distribution, as proven in [7].

Measuring  $m$  reflects  $i$  yields  $m$  estimates

$$\rho_i(\alpha_x, \beta_x, S_{r,i}) = \frac{\chi_a + 1/a_{ai}}{\chi_b + 1/a_{bi}} \approx \rho_* + \Delta\rho_i \quad (61)$$

with  $\rho_*$  the exact zero-order value and  $\Delta\rho_i = e_i$  the first-order measurement error. The unknown  $\vec{x}$  in (52) is the complex  $\rho$ , and  $A$  reduces to a column of ones. The covariance matrix can be calculated for the one-line TLR case using Marks' results [3, eqs. 46, 47] for  $\Delta\alpha$ ,  $\Delta\beta$  and error model for the computation of  $\Delta S_{r11}$ ,  $\Delta S_{r22}$ . A first-order series expansion allows to write (61). The result is diagonal dominant with

$$V_{ii} \propto (1 + |\Gamma_{ri}|^2)^2 \left( \frac{|\det(S_a)|^2}{|a_{a0i}|^4} + \frac{|\det(S_b)|^2}{|a_{b0i}|^4} \right) \quad (62)$$

which can be approximated using  $\det(S_a) = \det(S_b)$ ,  $|\Gamma_r| = 1$  and  $a_{x0} = a_x$ . The off-diagonal elements vanish if  $\sigma_\alpha$ ,  $\sigma_\beta$  and  $\sigma_{\alpha\beta}$  are small compared to  $\sigma_a$ , which is true for multi-line TLR. The estimator (56) thus reduces to a weighted average with weights  $1/V_{ii}$ .

## 6 Error box normalization

The method in section 5 estimates the port 1 reflections  $\alpha_a$ ,  $\alpha_b$  and  $\chi_a$ ,  $\chi_b$ ,  $p$ ,  $\rho$ . The 7-term relative error model follows from

$$S_{a21}S_{a12} \approx k_1 = se^{\gamma l} \sqrt{\frac{p}{\rho}} \quad (63)$$

$$S_{b21}S_{b12} \approx k_2 = \rho k_1 \quad (64)$$

$$S_{a22} \approx \chi_a k_1 \quad (65)$$

$$S_{b22} \approx \chi_b k_2 \quad (66)$$

$$S_{a21}S_{b12} \approx k_3 = e^{\gamma l} S_{t21}(1 - e) \quad (67)$$

$$S_{b21}S_{a12} \approx k_4 = e^{\gamma l} S_{t12}(1 - e) \quad (68)$$

where  $S_{a21}$  is usually set to unity. The sign  $s = \pm 1$  is chosen such that the recovered reflection, from (48), approximates an open or short.

The 8-term absolute error model can be recovered if the reciprocity ratio is known for the selected normalization. However,  $D_a$  and  $D_b$  can not be set freely since the ratios are related by

$$D_x = \frac{S_{x21}}{S_{x12}} \Rightarrow \frac{D_b}{D_a} \approx \frac{k_4}{k_3} \quad (69)$$

where  $k_4/k_3$  is unity to measurement precision if both error boxes are identical in terms of reciprocity. A plausible method is to distribute the error over  $D_a$  and  $D_b$  around the expected  $D_s$  via

$$D_a D_b = D_s^2 \Rightarrow D_a \approx s_1 D_s \sqrt{k_3/k_4} \quad (70)$$

$$\Rightarrow S_{a21} \approx s_2 \sqrt{k_1 D_a}. \quad (71)$$

The sign  $s_i = \pm 1$  is chosen such that the obtained value approximates  $e^{-j\omega\tau_i}$ , where  $\tau_i$  is an adaptive estimation from previous frequency points with initial value zero.

A good alternative for reciprocal error boxes is to set  $D_s$  to unity such that  $D_x \approx 1$ . This yields voltage normalized S-parameters, (31), if the reciprocity factor  $K = 1$ . The method supposes that the same renormalization at each port 2 yields a unity reciprocity ratio. Inconsistencies may arise when contacting lines on a lossy silicon substrate with different pitch probes. The transverse substrate currents[8] give an axial magnetic field, and the on-wafer modal voltage may thus depend on the probe pitch.

## 7 Experiment

A HP8510 network analyzer was calibrated by an on-wafer probe tip LRM calibration on a Cascade coplanar alumina substrate. The error boxes relate the raw VNA readout with the on-wafer S-parameters. A microwave test set samples the incident wave using a power splitter before the attenuator. The reflected wave is sampled using a directional coupler at the test set port. Thus,  $S_{x21}$  mainly describes the attenuator and cable loss, where  $S_{x12}$  comprises the same cable loss and the coupling coefficient. Reciprocity is clearly not valid since the forward and backward wave follow different detection paths. Nevertheless, using  $D_s = 1$  in (70) allows to estimate  $S_{a21}$  if the attenuator loss, at 0 dB setting, and coupling are about the same. The deviation of  $D_x$  from unity tracks the difference in reciprocity ratio between the two test set ports, see (69) and fig. 4.

The trans-calibration LRM to TLR error boxes were computed using multi-line TLR on the same alumina substrate. These error boxes relate the LRM reference plane, at port 1 in fig. 3, to the TLR reference plane, at port 2. The normalized (26) reciprocity ratio becomes[9]

$$D_x = \frac{S_{x21}}{S_{x12}} = \frac{D_x^{TLR}}{D_x^{LRM}} = \frac{K_{x2}^{LRM}}{K_{x2}^{TLR}} \quad (72)$$

and is unity since the modal field is quasi-TM. The reciprocity error  $|D_x - 1|$  was about  $10^{-4}$  up to 50 GHz. The cross-reflection  $e$ , see (41) and fig. 5, is high at low frequency due to a reference impedance change, a result of the non-ideal coplanar waveguide line standard. The difference between the two estimates (41), from forward and reverse measurements, indicates a repeatability error better than  $-40$  dB. The recovered reflection of the open standard shows a slight improvement if an extra short is used via (62).

The ratios  $D_a$ ,  $D_b$  and the final  $S_{a21}$  for another trans-wafer calibration are also given. The on-wafer

TLR calibration was done on a lossy silicon substrate using 150  $\mu\text{m}$  probes.  $D_a$  differs from unity up to  $10^{-3}$ , which is thus the expected measurement accuracy. The difference between the estimates  $e$ ,  $\text{dB}(e_1 - e_2)/2$ , increases from  $-44$  dB up to  $-32$  dB at 50 GHz. The high  $S_{11}$  is due to a change in reference impedance, from the LRM 50  $\Omega$  to the coplanar waveguide line impedance. This lower accuracy might be a result of inaccurate probing. Also, the non-TM on-wafer modal field might increase the measurement's sensitivity on the probe placing.

## 8 Conclusion

The Lorentz reciprocity theorem, a field property, was used to derive a reciprocity ratio relating the forward and reverse transmission coefficient. The ratio depends on the characteristic impedance and a reciprocity factor. From power consistency, between the field and the macroscopic circuit parameters, follows that the factor is unity for TE or TM junctions. The characteristic impedance dependence can be removed using a suitable voltage renormalization.

An alternative TLR 7-term error box calculation sequence was presented. It is transmission coefficient based and remains valid even if an error box reflection is zero. Extensions of the algorithm include the zero- and multi-reflect case, and LRM modifications. The reciprocity condition was used to extract an absolute 8-term error model. Implicit assumptions and possible inconsistencies were demonstrated.

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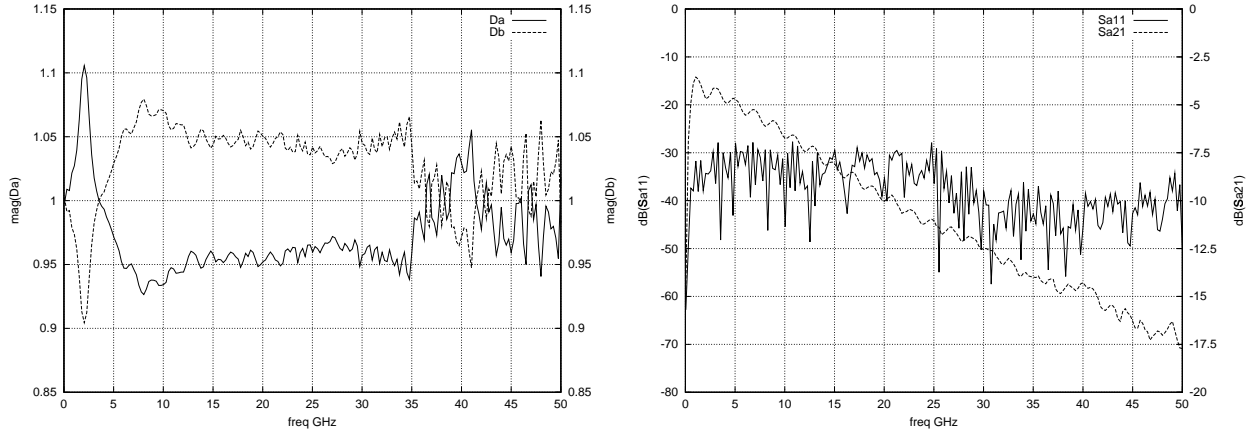


Figure 4: The ratio  $D_a, D_b$  and  $S_{a11}, S_{a21}$  for a probe tip on-wafer LRM calibration. A microwave test set is not reciprocal, but assuming a unity reciprocity ratio allows for some estimate of  $S_{a21}$ . The error box consists of the test set detection circuit, the 1 m coaxial cable and the 100  $\mu\text{m}$  pitch microwave probe. The reciprocity difference between the test set ports,  $D_b/D_a$ , peaks at 0.8, about  $-1.7$  dB.

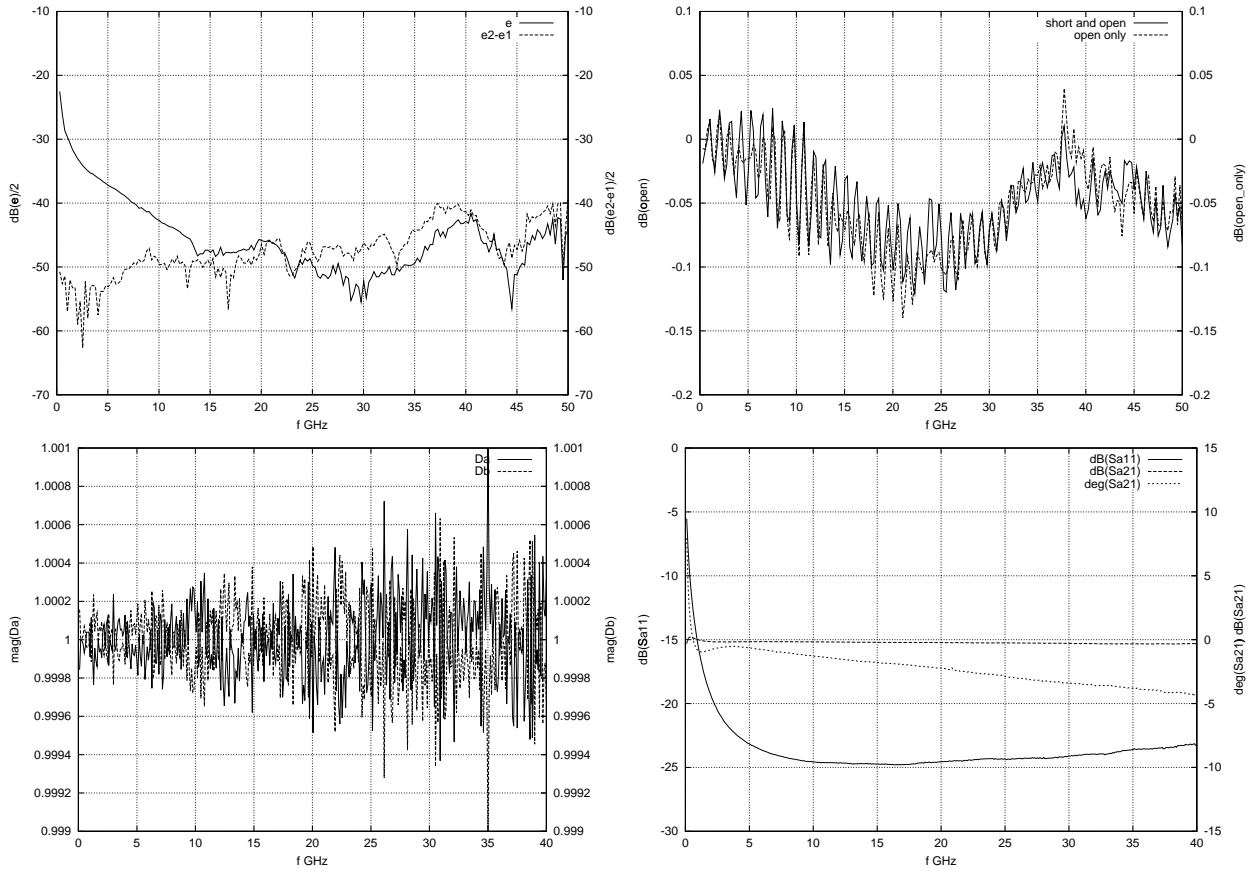


Figure 5: Top: The factor  $e$  and the difference between the two estimates, left, and the recovered reflection of an open, using the short and open calibration standard, or the open standard only. The plots are from a LRM to TLR trans-calibration, both performed on an alumina calibration substrate. The 6 cpw lines, 50/25/200  $\mu\text{m}$  strip/slot/ground plane, were 197.4, 432.9, 870.9, 1736.8, 1736.8, 3383.1 and 5080  $\mu\text{m}$  long. Bottom: The ratio  $D_a, D_b$  and the recovered S-parameters of error box a. The plots are for a 0.5  $\mu\text{m}$  thick Al 15/11/183  $\mu\text{m}$  coplanar line separated from a 5 S/m Si substrate by a 1  $\mu\text{m}$  thick dielectric. LRM was used as off-wafer calibration.



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